



# Asus AAEON BOXER-8621AI User Manual

Ai@edge compact fanless embedded ai system with nvidia jetson orin nano



1

2

3

4

5

6

7

8

9

10

Table Of Contents

11

12

13

14

15

16

17

18  
19  
20  
21  
22  
23  
24  
25  
26  
27  
28  
29  
30  
31  
32  
33  
34  
35  
36  
37  
38  
39  
40  
41  
42  
43  
44  
45  
46  
47  
48  
49  
50  
51

--

•

[Table of Contents](#)

•

Bookmarks

--

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# BOXER-8621AI

AI@Edge Compact Fanless Embedded  
AI System with NVIDIA



®

Jetson Orin Nano

™

User's Manual 1

st

[Table of Contents](#)

[Next Page](#)

1  
2  
3  
4  
5

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## Summary of Contents for Asus AAEON BOXER-8621AI

[Page 1](#) BOXER-8621AI AI@Edge Compact Fanless Embedded AI System with NVIDIA ® Jetson Orin Nano™ User's Manual 1 Last Updated: August 16, 2023...

[Page 2](#) Copyright Notice This document is copyrighted, 2023. All rights are reserved. The original manufacturer reserves the right to make improvements to the products described in this manual at any time without notice. No part of this manual may be reproduced, copied, translated, or transmitted in any form or by any means without the prior written permission of the original manufacturer.

[Page 3](#) Acknowledgements All other products' name or trademarks are properties of their respective owners. NVIDIA®, the NVIDIA logo, Jetson™, Jetson Orin Nano™, and JetPack™ are ● trademarks of the NVIDIA Corporation. Arm® and Arm®v8-M architecture are registered trademarks of Arm Limited. ●...

**Page 4** Packing List Before setting up your product, please make sure the following items have been shipped: Item Quantity BOXER-8621AI • Wallmount Bracket • Screw Package • Power Connector • Power Adapter (Optional) • Power Cord (Optional) • If any of these items are missing or damaged, please contact your distributor or sales representative immediately.

**Page 5** About this Document This User's Manual contains all the essential information, such as detailed descriptions and explanations on the product's hardware and software features (if any), its specifications, dimensions, jumper/connector settings/definitions, and driver installation instructions (if any), to facilitate users in setting up their product. Users may refer to the product page at [AAEON.com](http://AAEON.com) for the latest version of this document.

**Page 6** Safety Precautions Please read the following safety instructions carefully. It is advised you keep this manual for future references All cautions and warnings on the device should be noted. All cables and adapters supplied by AAEON are certified and in accordance with the material safety laws and regulations of the country of sale.

**Page 7** As most electronic components are sensitive to static electrical charge, be sure to ground yourself to prevent static charge when installing the internal components. Use a grounding wrist strap and contain all electronic components in any static-shielded containers. If any of the following situations arises, please the contact our service personnel: Damaged power cord or plug Liquid intrusion to the device iii.

**Page 8** FCC Statement This device complies with Part 15 FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received including interference that may cause undesired operation.

**Page 9** China RoHS Requirements (CN) AAEC System Q04-381 Rev.A0  
 (PBDE) (Pb) (Hg) (Cd) (Cr(VI)) (PBB)  
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**Page 10** China RoHS Requirement (EN) Hazardous and Toxic Materials List AAEON System  
QO4-381 Rev.A0 Hazardous or Toxic Materials or Elements Component Name PCB and  
Components Wires & Connectors for Ext.Connections Chassis CPU & RAM HDD Drive LCD  
Module Optical Drive Touch Control Module Battery This form is prepared in compliance with the  
provisions of SJ/T 11364.

[Page 11: Table Of Contents](#)

Table of Contents Chapter 1 - Product Specifications.....	1 Specifications .....	2
Chapter 2 - Hardware Information .....	4 Dimensions .....	5
Jumpers and Connectors .....	6 List of Jumpers .....	8
2.3.1 Jumper Settings .....	8	
2.3.2 AT/ATX Mode Selection (CN2) .....	9 List of Connectors .....	

<a href="#">Page 12</a>	2.4.18 M.2 3052 B-Key (CN21) .....	24 Hardware Installation .....	25
	2.5.1 Expansion Module Installation .....	25 Chapter 3 – BSP Flash Guide .....	30
	Before Installation .....	31 Connecting to PC/Force Recovery Mode .....	32
	Flash Image to Board .....	34 Check BSP Version .....	

## Page 13: Chapter 1 - Product Specifications

Chapter 1 Chapter 1 - Product Specifications...

## Page 14: Specifications

Specifications System AI Accelerator NVIDIA® Jetson Orin Nano™ 6-Core Arm® Cortex®-A78AE v8.2 64-bit CPU System Memory 4GB LPDDR5/8GB LPDDR5 Storage Device M.2 3052 B-Key x 1 for M.2 2242 B+M-Key SSD (Default Storage) M.2 2230 E-Key x 1 (Optional) Display Interface HDMI 1.4 (Type-A) x 1 Ethernet RJ-45 x 1 for GbE LAN...

**Page 15** Power Supply Power Requirement 12V~24V DC in with 2-pin Terminal Block x 1  
Mechanical Mounting Wallmount Dimensions (W x D x H) 4.13" x 3.54" x 2.05" (105mm x 90mm x 52mm) w/o Bracket Gross Weight 2.4 lb. (1.1Kg) Net Weight 1.58 lb.

## [Page 16: Chapter 2 - Hardware Information](#)

Chapter 2 Chapter 2 – Hardware Information...

## [Page 17: Dimensions](#)

Dimensions Chapter 2 – Hardware Information...

## [Page 18: Jumpers And Connectors](#)

Jumpers and Connectors Chapter 2 – Hardware Information...

## [Page 19](#) Bottom Chapter 2 – Hardware Information...

## [Page 20: List Of Jumpers](#)

List of Jumpers The board has a number of jumpers that allow you to configure your system to suit your application. The table below shows the function of each of the board's jumpers Label Function AT/ATX Mode Selection 2.3.1 Jumper Settings You configure your card to match the needs of your application by setting jumpers.

## [Page 21: At/Atx Mode Selection \(Cn2\)](#)

2.3.2 AT/ATX Mode Selection (CN2) CN2 Pin Function Close ATX Open AT (Default) Chapter 2 – Hardware Information...

## [Page 22: List Of Connectors](#)

List of Connectors The board has a number of connectors that allow you to configure your system to suit your application. The table below shows the function of each of the board's connectors Label Function NVIDIA Jetson Orin Nano Connector Front Panel Connector RTC Battery Connector Micro USB for Flash OS...

## [Page 23: Front Panel Connector \(Cn2\)](#)

2.4.1 Front Panel Connector (CN2) Signal Signal Button power Recovery System Reset AC OK PD 10Kohm 3.3V AO 5V AO 2.4.2 RTC Connector (CN3) Signal Signal Chapter 2 – Hardware Information...

## [Page 24: Micro Usb \(Flash Os\) \(Cn4\)](#)

2.4.3 Micro USB (Flash OS) (CN4) Signal Signal USB1- USB1+ 2.4.4 HDMI Connector (CN5) Signal Signal HDMI\_DATA2\_P HDMI\_DATA2\_N HDMI\_DATA1\_P HDMI\_DATA1\_N HDMI\_DATA0\_P HDMI\_DATA0\_N HDMI\_CLK\_P HDMI\_CLK\_N HDMI\_SCL HDMI\_SDA Chapter 2 – Hardware Information...

## [Page 25: Com Port Connector \(Rs-232 + Canbus\) \(Cn6\)](#)

Signal Signal HDMI\_PWR HDMI\_HDP 2.4.5 COM Port Connector (RS-232 + CANBus) (CN6) RS-232 CANBus CAN0\_L CAN0\_H RTS# CTS# Chapter 2 – Hardware Information...

## [Page 26](#) DB-9 Port (Male) RS-232 CANBus CAN0\_L CAN0\_H RTS# CTS# Chapter 2 – Hardware Information...

## [Page 27: Com Port Connector \(Rs-232/422/485\) \(Cn7/Sw2\)](#)

2.4.6 COM Port Connector (RS-232/422/485) (CN7/SW2) RS-232 RS-422 CANBus TXD- TXD- RXD+ TXD+ TXD+ RXD- Chapter 2 – Hardware Information...

## [Page 28: Rs-232/422/485 Select \(Sw2\)](#)

2.4.7 RS-232/422/485 Select (SW2) Mode 1T/1R RS-232 1T/1R RS-422 1T/1R RS-485 Low power shutdown 250kbps for RS-232 and RS-485/RS-422 RS-232 to 3Mbps and RS-485/RS-422 to 20Mbps Enable RS-422/RS-485 Bias and Termination Resistors. Disable RS-422/RS-485 Bias and Termination Resistors. Chapter 2 – Hardware Information...

## [Page 29: Dio Port Connector \(Cn8\)](#)

2.4.8 DIO Port Connector (CN8) Function DTS Name GPIO GPIO13 PH.00 I2S0 LRCK PI.02 GPIO11 PQ.06 I2S0 SDIN PI.01 GPIO09 PAC.06 I2S0 SDOOUT PI.00 GPIO01 PQ.05 I2S0 SCLK PH.07 Chapter

### [Page 30: Com+Dio Port Connector \(Cn7+Cn8/Sw2\)](#)

2.4.9 COM+DIO port Connector (CN7+CN8/SW2) DB-15 Port (Female) RS-232 RS-422 RS-485  
Function DTS Name GPIO No. GPIO13 PH.00 GPIO11 PQ.06 GPIO09 PAC.06 GPIO01 PQ.05  
I2S0\_LRCK PI.02 I2S0\_SDIN PI.01 I2S0\_SDOOUT PI.00 I2S0\_SCLK PH.07 Chapter 2 – Hardware  
Information...

### [Page 31: Uart Debug Port Connector \(Cn9\)](#)

2.4.10 UART Debug Port Connector (CN9) Signal VCC 3.3V UART TX UART RX 2.4.11 RJ-45  
Connector (CN10) Signal Signal MDI0+ MDI0- MDI1+ MDI1- MDI2+ MDI2- MDI3+ MDI3- Note:  
Speed LED 1000Base-T Green, 10/100Base-T no LED. Chapter 2 – Hardware Information...

### [Page 32: 2230 E-Key \(Cn11\)](#)

2.4.12 M.2 2230 E-Key (CN11) Chapter 2 – Hardware Information...

### [Page 33: Connector \(Cn10\)](#)

2.4.13 RJ-45 Connector (CN10) Signal Signal MDI0+ MDI0- 2.4.14 USB 3.2 Gen 2 Type-A Port  
(CN13) Signal Signal VBUS\_1 VBUS\_2 (A)D- (B)D- (A)D+ (B)D+ (A)SSRX- (B)SSRX- (A)SSRX+  
(B)SSRX+ Chapter 2 – Hardware Information...

### [Page 34: Usb 2.0 Type-A Port \(Cn14\)](#)

Signal Signal (A)SSTX- (B)SSTX- (A)SSTX+ (B)SSTX+ 2.4.15 USB 2.0 Type-A Port (CN14) Signal  
Signal VBUS\_1 VBUS\_2 (A)D- (B)D- (A)D+ (B)D+ 2.4.16 DC Power In Connector (CN19) Signal  
Signal PWR\_IN Chapter 2 – Hardware Information...

### [Page 35: Nano Sim Connector \(Cn20\)](#)

2.4.17 Nano SIM Connector (CN20) Signal Chapter 2 – Hardware Information...

### [Page 36: 3052 B-Key \(Cn21\)](#)

2.4.18 M.2 3052 B-Key (CN21) Chapter 2 – Hardware Information...

### [Page 37: Hardware Installation](#)

Hardware Installation 2.5.1 Expansion Module Installation Before installing your expansion  
module, ensure the system is powered down and disconnect the power cord from the system.  
Make sure you have the expansion module(s) ready to install. See Chapter 1 for expansion  
module specifications for compatibility.

[Page 38](#) To access the interior, first remove the four (4) screws on the bottom of the chassis,  
as shown. Chapter 2 – Hardware Information...

[Page 39](#) M.2 3042 B-Key (M.2 2242 B + M-Key Storage Module) Chapter 2 – Hardware  
Information...

[Page 40](#) M.2 3052 B-Key Chapter 2 – Hardware Information...

[Page 41](#) M.2 2230 E-Key Chapter 2 – Hardware Information...

### [Page 42: Chapter 3 - Bsp Flash Guide](#)

Chapter 3 Chapter 3 – BSP Flash Guide...

### [Page 43: Before Installation](#)

Before Installation Before starting the process make sure your BOXER-8621AI system is turned  
off and the power is disconnected. You will need a Host PC running Ubuntu 18.04, and make  
sure the NVIDIA® Jetson Orin Nano™ module is installed onto the BOXER-8621AI carrier board  
system.



## [Page 44: Connecting To Pc/Force Recovery Mode](#)

Connecting to PC/Force Recovery Mode Step 1: On the Host computer, open Linux terminal and enter the following command to extract the compressed BSP image files (BSP file name may vary): `$ sudo tar -zxvf BOXER_8621AI_J5.1.1_A00_1.0.0_20230519.tar.gz` Note: Do not decompress the file (Internal.tar.gz) using a Windows OS, BSP should only be decompressed in a Linux EXT3/4 file system.

[Page 45](#) Step 2: Perform the following actions to force the system to start in USB Recovery Mode: Connect the Micro-USB plug on the USB cable to the Recovery Port on the BOXER-8621AI and the other end to an available USB port on the Host PC. Connect the BOXER-8621AI to a power supply.

## [Page 46: Flash Image To Board](#)

Flash Image to Board Use the following steps to flash the OS to the BOXER-8621AI. Open terminal on the Ubuntu Host PC, then access the folder you extracted in the previous section. Enter the following command in terminal to flash the image: `$ ./flashboxer.sh -s 62517420 nvme` Wait until the image is installed.

## [Page 47: Check Bsp Version](#)

Check BSP Version Once the flash image is successfully installed, the BOXER-8621AI will reboot automatically, then check the BSP version to see if the system is flashing the correct version of BSP . Open a Terminal, and type command "`cat /proc/product`"...

## [Page 48: Chapter 4 - Os User Guide](#)

Chapter 4 Chapter 4 – OS User Guide...

## [Page 49: Introduction](#)

Introduction The BOXER-8621AI's OS, Ubuntu/Linux version, and preinstalled SDK components are as follows: Jetpack 5.1.1 (L4t 35.3.1) Ubuntu/Linux version Ubuntu version: 20.04.6 Kernel version: 5.10.104-tegra UEFI version: 3.1-32827747 Built-in all Jetson SDK Components CUDA Toolkit for L4T 11.4.19 cuDNN 8.6.0 TensorRT 8.5.2 OpenCV 4.5.4 VPI 2.2...

## [Page 50: Update Note](#)

Update Note Running `$ sudo apt upgrade` command in terminal will overwrite the Aaeon kernel device tree (.dtb)/kernel image(Image)/bootloader in OS, which can lead to unexpected results including losing I/O ports. So Aaeon default disable Nvidia apt Repo for updating Nvidia apt package.

## [Page 51: Boxer-8621Ai Power Mode](#)

BOXER-8621AI Power Mode NVIDIA® Jetson Orin Nano™ power mode can be selected and monitored by GUI, please refer to the following picture: Note: Power mode is dependent on DRAM size. For more detailed information please visit <https://developer.nvidia.com/embedded/jetson-modules> Chapter 4 – OS User Guide...