



Asus AAEON BOXER-8651AI User Manual

Ai@edge compact fanless embedded ai system with nvidia jetson orin nx

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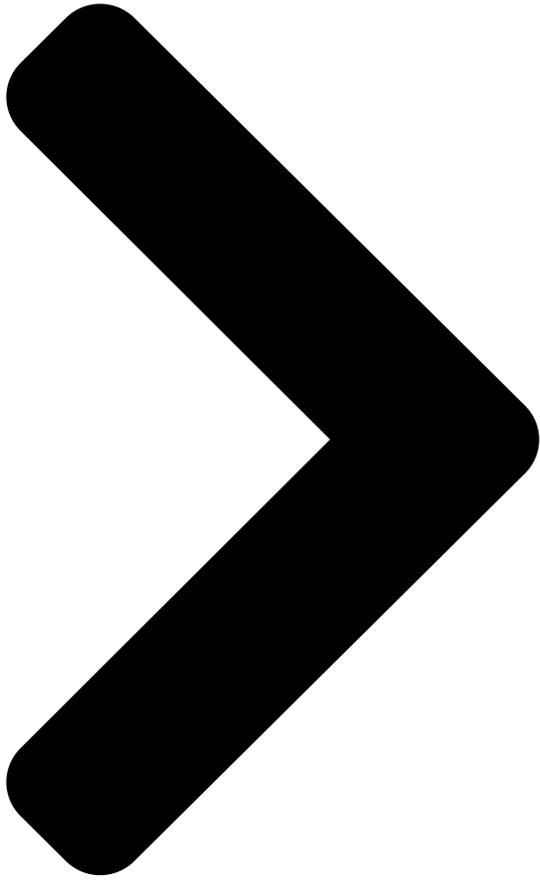
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List of Jumpers The board has a number of jumpers that allow you to configure your system to suit your application. The table below shows the function of each of the board's jumpers Label Function AT/ATX Mode Selection 2.3.1 Jumper Settings You configure your card to match the needs of your application by setting jumpers.

[Page 21: At/Atx Mode Selection \(Cn2\)](#)

2.3.2 AT/ATX Mode Selection (CN2) CN2 Pin Function Close ATX Open AT (Default) Chapter 2 - Hardware Information...

[Page 22: List Of Connectors](#)

List of Connectors The board has a number of connectors that allow you to configure your system to suit your application. The table below shows the function of each of the board's connectors Label Function NVIDIA Jetson Orin NX Connector Front Panel Connector RTC Battery Connector Micro USB for Flash OS...

[Page 23: Front Panel Connector \(Cn2\)](#)

2.4.1 Front Panel Connector (CN2) Signal Signal Button power Recovery System Reset AC OK PD 10Kohm 3.3V AO 5V AO 2.4.2 RTC Connector (CN3) Signal Signal Chapter 2 - Hardware Information...

[Page 24: Micro Usb \(Flash Os\) \(Cn4\)](#)

2.4.3 Micro USB (Flash OS) (CN4) Signal Signal USB1- USB1+ 2.4.4 HDMI Connector (CN5) Signal Signal HDMI_DATA2_P HDMI_DATA2_N HDMI_DATA1_P HDMI_DATA1_N HDMI_DATA0_P HDMI_DATA0_N HDMI_CLK_P HDMI_CLK_N HDMI_SCL HDMI_SDA Chapter 2 - Hardware Information...

[Page 25: Com Port Connector \(Rs-232 + Canbus\) \(Cn6\)](#)

Signal Signal HDMI_PWR HDMI_HDP 2.4.5 COM Port Connector (RS-232 + CANBus) (CN6) RS-232 CANBus CAN0_L CAN0_H RTS# CTS# Chapter 2 - Hardware Information...

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[Page 27: Com Port Connector \(Rs-232/422/485\) \(Cn7/Sw2\)](#)

2.4.6 COM Port Connector (RS-232/422/485) (CN7/SW2) RS-232 RS-422 CANBus TXD- TXD- RXD+ TXD+ TXD+ RXD- Chapter 2 - Hardware Information...

[Page 28: Rs-232/422/485 Select \(Sw2\)](#)

2.4.7 RS-232/422/485 Select (SW2) Mode 1T/1R RS-232 1T/1R RS-422 1T/1R RS-485 Low power shutdown 250kbps for RS-232 and RS-485/RS-422 RS-232 to 3Mbps and RS-485/RS-422 to 20Mbps Enable RS-422/RS-485 Bias and Termination Resistors. Disable RS-422/RS-485 Bias and Termination Resistors. Chapter 2 - Hardware Information...

[Page 29: Dio Port Connector \(Cn8\)](#)

2.4.8 DIO Port Connector (CN8) Function DTS Name GPIO GPIO13 PH.00 I2S0 LRCK PI.02 GPIO11 PQ.06 I2S0 SDIN PI.01 GPIO09 PAC.06 I2S0 SDOOUT PI.00 GPIO01 PQ.05 I2S0 SCLK PH.07 Export

GPIO then you can control GPIO from user space through sysfs. For example: GPIO ID:PY.02
Export PY.02...

[Page 30: Com+Dio Port Connector \(Cn7+Cn8/Sw2\)](#)

```
2. Set GPIO direction to input mode # echo "in" > /sys/class/gpio/PY.02/direction # cat  
/sys/class/gpio/PY.02/value #Read GPIO input value Unexport PY.02 # echo PY.02 >  
/sys/class/gpio/unexport 2.4.9 COM+DIO port Connector (CN7+CN8/SW2) DB-15 Port (Female)  
RS-232 RS-422 RS-485 Function DTS Name GPIO No.
```

[Page 31: Uart Debug Port Connector \(Cn9\)](#)

RS-232 RS-422 RS-485 I2S0_SCLK PH.07 2.4.10 UART Debug Port Connector (CN9) Signal VCC
3.3V UART TX UART RX 2.4.11 RJ-45 Connector (CN10) Signal Signal MDIO+ MDIO- MDI1+ MDI1-
MDI2+ MDI2- MDI3+ MDI3- Note: Speed LED 1000Base-T Green, 10/100Base-T no LED. Chapter
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[Page 32: 2230 E-Key \(Cn11\)](#)

2.4.12 M.2 2230 E-Key (CN11) Chapter 2 - Hardware Information...

[Page 33: Connector \(Cn10\)](#)

2.4.13 RJ-45 Connector (CN10) Signal Signal MDIO+ MDIO- 2.4.14 USB 3.2 Gen 2 Type-A Port
(CN13) Signal Signal VBUS_1 VBUS_2 (A)D- (B)D- (A)D+ (B)D+ (A)SSRX- (B)SSRX- (A)SSRX+
(B)SSRX+ Chapter 2 - Hardware Information...

[Page 34: Usb 2.0 Type-A Port \(Cn14\)](#)

Signal Signal (A)SSTX- (B)SSTX- (A)SSTX+ (B)SSTX+ 2.4.15 USB 2.0 Type-A Port (CN14) Signal
Signal VBUS_1 VBUS_2 (A)D- (B)D- (A)D+ (B)D+ 2.4.16 DC Power In Connector (CN19) Signal
Signal PWR_IN Chapter 2 - Hardware Information...

[Page 35: Nano Sim Connector \(Cn20\)](#)

2.4.17 Nano SIM Connector (CN20) Signal Chapter 2 - Hardware Information...

[Page 36: 3052 B-Key \(Cn21\)](#)

2.4.18 M.2 3052 B-Key (CN21) Chapter 2 - Hardware Information...

[Page 37: Hardware Installation](#)

Hardware Installation 2.5.1 Expansion Module Installation Before installing your expansion
module, ensure the system is powered down and disconnect the power cord from the system.
Make sure you have the expansion module(s) ready to install. See Chapter 1 for expansion
module specifications for compatibility.

[Page 38](#) To access the interior, first remove the four (4) screws on the bottom of the chassis,
as shown. Chapter 2 - Hardware Information...

[Page 39](#) M.2 3042 B-Key (M.2 2242 B + M-Key Storage Module) Chapter 2 - Hardware
Information...

[Page 40](#) M.2 3052 B-Key Chapter 2 - Hardware Information...

[Page 41](#) M.2 2230 E-Key Chapter 2 - Hardware Information...

[Page 42: Chapter 3 - Bsp Flash Guide](#)

Chapter 3 Chapter 3 - BSP Flash Guide...

[Page 43: Before Installation](#)

Before Installation Before starting the process make sure your BOXER-8651AI system is turned
off and the power is disconnected. You will need a Host PC running Ubuntu 18.04, and make
sure the NVIDIA® Jetson Orin™ NX module is installed onto the BOXER-8651AI carrier board

system.

[Page 44: Connecting To Pc/Force Recovery Mode](#)

Connecting to PC/Force Recovery Mode Step 1: On the Host computer, open Linux terminal and enter the following command to extract the compressed BSP image files (BSP file name may vary): `$ sudo tar -zxvf BOXER_8651AI_J5.1.1_A00_1.0.2_20230822.tar.gz` Note: Do not decompress the file (Internal.tar.gz) using a Windows OS, BSP should only be decompressed in a Linux EXT3/4 file system.

[Page 45](#) Press and hold the recovery key button. While holding the recovery key button, power on the system, and continue to hold the recovery key button for two seconds, then release. The BOXER-8651AI should then enter recovery mode. To check if device is in recovery mode, enter the `lsusb` command in the terminal on the Host PC.

[Page 46: Flash Image To Board](#)

Flash Image to Board Use the following steps to flash the OS to the BOXER-8651AI. Open terminal on the Ubuntu Host PC, then access the folder you extracted in the previous section. Enter the following command in terminal to flash the image: `$./flashboxer.sh -s 62517420 nvme` Wait until the image is installed.

[Page 47: Check Bsp Version](#)

Check BSP Version Once the flash image is successfully installed, the BOXER-8651AI will reboot automatically, then check the BSP version to see if the system is flashing the correct version of BSP . Open a Terminal, and type command "`cat /proc/product`"...

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Chapter 4 Chapter 4 - OS User Guide...

[Page 49: Introduction](#)

Introduction The BOXER-8651AI's OS, Ubuntu/Linux version, and preinstalled SDK components are as follows: Jetpack 5.1.1 (l4t 35.3.1) Ubuntu/Linux version Ubuntu version: 20.04.6 Kernel version: 5.10.104-tegra UEFI version: 3.1-32827747 Built-in all Jetson SDK Components CUDA Toolkit for L4T 11.4.19 cuDNN 8.6.0 TensorRT 8.5.2 OpenCV 4.5.4 VPI 2.2...

[Page 50: Update Note](#)

Update Note Running `$ sudo apt upgrade` command in terminal will overwrite the Aaeon kernel device tree (.dtb)/kernel image(Image)/bootloader in OS, which can lead to unexpected results including losing I/O ports. So Aaeon default disable Nvidia apt Repo for updating Nvidia apt package.

[Page 51: Boxer-8651Ai Power Mode](#)

BOXER-8651AI Power Mode NVIDIA® Jetson Orin™ NX power mode can be selected and monitored by GUI, please refer to the following picture: Note: Power mode is dependent on DRAM size. For more detailed information please visit <https://developer.nvidia.com/embedded/jetson-modules> Chapter 4 - OS User Guide...